

```
# DIFF
###WARNING: NO CUSTOM DEFAULTS FOUND###
# version
# Betaflight / STM32F405 (S405) 4.3.1 Jul 13 2022 / 03:32:11 (8d4f005) MSP API: 1.44
###ERROR IN diff: NO CONFIG FOUND###
# start the command batch
batch start
board_name FLYWOOOF405NANO
manufacturer_id FLWO
# name: FLYWOO
# resources
resource BEEPER 1 C13
resource MOTOR 1 B00
resource MOTOR 2 B01
resource MOTOR 3 A03
resource MOTOR 4 A02
resource MOTOR 5 B05
resource MOTOR 6 C09
resource MOTOR 7 B07
resource MOTOR 8 C08
resource PPM 1 B08
resource LED_STRIP 1 A09
resource SERIAL_TX 1 B06
resource SERIAL_TX 2 D05
resource SERIAL_TX 3 B10
resource SERIAL_TX 4 A00
resource SERIAL_TX 6 C06
resource SERIAL_RX 1 A10
resource SERIAL_RX 2 D06
resource SERIAL_RX 3 B11
resource SERIAL_RX 4 A01
resource SERIAL_RX 5 D02
resource SERIAL_RX 6 C07
resource I2C_SCL 1 B08
resource I2C_SDA 1 B09
resource LED 1 C14
resource SPI_SCK 1 A05
resource SPI_SCK 3 C10
resource SPI_MISO 1 A06
resource SPI_MISO 3 C11
resource SPI_MOSI 1 A07
resource SPI_MOSI 3 C12
resource ESCSERIAL 1 B08
resource ADC_BATT 1 C03
resource ADC_RSSI 1 C00
resource ADC_CURR 1 C02
resource FLASH_CS 1 B03
resource OSD_CS 1 B14
```

resource GYRO\_EXTI 1 B13  
resource GYRO\_CS 1 B12  
resource USB\_DETECT 1 A08  
# timer  
timer B00 AF2  
# pin B00: TIM3 CH3 (AF2)  
timer B01 AF2  
# pin B01: TIM3 CH4 (AF2)  
timer A03 AF1  
# pin A03: TIM2 CH4 (AF1)  
timer A02 AF1  
# pin A02: TIM2 CH3 (AF1)  
timer B05 AF2  
# pin B05: TIM3 CH2 (AF2)  
timer B07 AF2  
# pin B07: TIM4 CH2 (AF2)  
timer C09 AF3  
# pin C09: TIM8 CH4 (AF3)  
timer C08 AF3  
# pin C08: TIM8 CH3 (AF3)  
timer A09 AF1  
# pin A09: TIM1 CH2 (AF1)  
# dma  
dma ADC 1 0  
# ADC 1: DMA2 Stream 0 Channel 0  
dma pin B00 0  
# pin B00: DMA1 Stream 7 Channel 5  
dma pin B01 0  
# pin B01: DMA1 Stream 2 Channel 5  
dma pin A03 1  
# pin A03: DMA1 Stream 6 Channel 3  
dma pin A02 0  
# pin A02: DMA1 Stream 1 Channel 3  
dma pin B05 0  
# pin B05: DMA1 Stream 5 Channel 5  
dma pin B07 0  
# pin B07: DMA1 Stream 3 Channel 2  
dma pin C09 0  
# pin C09: DMA2 Stream 7 Channel 7  
dma pin C08 0  
# pin C08: DMA2 Stream 2 Channel 0  
dma pin A09 0  
# pin A09: DMA2 Stream 6 Channel 0  
# feature  
feature -RX\_PARALLEL\_PWM  
feature RX\_SERIAL  
feature MOTOR\_STOP  
feature TELEMETRY

```
feature LED_STRIP
feature OSD
# serial
serial 2 1 115200 57600 0 115200
serial 3 64 115200 57600 0 115200
# mixer
mixer HEX6X
# led
led 0 6,6::CO:8
led 1 7,6::CO:8
led 2 8,6::CO:8
led 3 9,6::CO:8
# aux
aux 0 0 1 1375 2100 0 0
aux 1 2 1 1700 2100 0 0
# vtxtable
vtxtable bands 5
vtxtable channels 8
vtxtable band 1 BAND_A A CUSTOM 5865 5845 5825 5805 5785 5765 5745 5725
vtxtable band 2 BAND_B B CUSTOM 5733 5752 5771 5790 5809 5828 5847 5866
vtxtable band 3 BAND_E E CUSTOM 5705 5685 5665 5645 5885 5905 5925 5945
vtxtable band 4 AIRWAVE F CUSTOM 5740 5760 5780 5800 5820 5840 5860 5880
vtxtable band 5 RACEBAND R CUSTOM 5658 5695 5732 5769 5806 5843 5880 5917
vtxtable powerlevels 5
vtxtable powervalues 25 100 200 400 600
vtxtable powerlabels 25 50 100 200 MAX
# rxfail
rxfail 6 s 2000
# master
set acc_calibration = -47,-112,-56,1
set mag_bustype = I2C
set mag_i2c_device = 1
set mag_hardware = NONE
set baro_bustype = I2C
set baro_i2c_device = 1
set serialrx_provider = SBUS
set blackbox_device = SPIFLASH
set dshot_burst = ON
set motor_pwm_protocol = DSHOT300
set current_meter = ADC
set battery_meter = ADC
set ibata_scale = 200
set beeper_inversion = ON
set beeper_od = OFF
set yaw_motors_reversed = ON
set pid_process_denom = 2
set osd_vbat_pos = 2305
set osd_rssi_pos = 2177
```

set osd\_rssi\_dbm\_pos = 161  
set osd\_tim\_1\_pos = 2401  
set osd\_tim\_2\_pos = 2369  
set osd\_flymode\_pos = 2241  
set osd\_throttle\_pos = 2361  
set osd\_vtx\_channel\_pos = 2209  
set osd\_current\_pos = 2391  
set osd\_mah\_drawn\_pos = 2273  
set osd\_craft\_name\_pos = 2081  
set osd\_gps\_speed\_pos = 2264  
set osd\_gps\_lon\_pos = 2129  
set osd\_gps\_lat\_pos = 2097  
set osd\_gps\_sats\_pos = 2167  
set osd\_home\_dir\_pos = 2190  
set osd\_home\_dist\_pos = 2200  
set osd\_flight\_dist\_pos = 2232  
set osd\_altitude\_pos = 2327  
set osd\_warnings\_pos = 2441  
set osd\_avg\_cell\_voltage\_pos = 2337  
set osd\_disarmed\_pos = 2411  
set osd\_flip\_arrow\_pos = 2113  
set osd\_core\_temp\_pos = 2296  
set osd\_log\_status\_pos = 2145  
set osd\_efficiency\_pos = 231  
set system\_hse\_mhz = 8  
set vtx\_band = 3  
set vtx\_channel = 4  
set vtx\_power = 5  
set vtx\_freq = 5645  
set max7456\_spi\_bus = 3  
set dashboard\_i2c\_bus = 1  
set pinio\_box = 40,41,255,255  
set flash\_spi\_bus = 3  
set gyro\_1\_bustype = SPI  
set gyro\_1\_spibus = 1  
set gyro\_1\_sensor\_align = CW90  
set gyro\_1\_align\_yaw = 900  
set gyro\_2\_spibus = 1  
set name = FLYWOO  
profile 0  
# profile 0  
set p\_pitch = 66  
set i\_pitch = 99  
set d\_pitch = 76  
set p\_roll = 61  
set i\_roll = 94  
set d\_roll = 70  
set f\_roll = 119

```
set p_yaw = 65
set i_yaw = 99
set f_yaw = 119
set d_min_roll = 46
set d_min_pitch = 51
set simplified_pids_mode = OFF
rateprofile 0
# end the command batch
batch end
#
SAVE
```