

DIFF

###WARNING: NO CUSTOM DEFAULTS FOUND###

version

Betaflight / STM32F405 (S405) 4.3.1 Jul 13 2022 / 03:32:11 (8d4f005) MSP API: 1.44

###ERROR IN diff: NO CONFIG FOUND###

start the command batch

batch start

board_name FLYWOOF405S_AIO

manufacturer_id FLWO

resources

resource BEEPER 1 C13

resource MOTOR 1 A03

resource MOTOR 2 B00

resource MOTOR 3 A02

resource MOTOR 4 B01

resource MOTOR 5 B05

resource MOTOR 6 B07

resource MOTOR 7 C09

resource MOTOR 8 C08

resource PPM 1 B08

resource LED_STRIP 1 A09

resource SERIAL_TX 1 B06

resource SERIAL_TX 2 D05

resource SERIAL_TX 3 B10

resource SERIAL_TX 4 A00

resource SERIAL_TX 6 C06

resource SERIAL_RX 1 A10

resource SERIAL_RX 2 D06

resource SERIAL_RX 3 B11

resource SERIAL_RX 4 A01

resource SERIAL_RX 5 D02

resource SERIAL_RX 6 C07

resource I2C_SCL 1 B08

resource I2C_SDA 1 B09

resource LED 1 C14

resource SPI_SCK 1 A05

resource SPI_SCK 3 C10

resource SPI_MISO 1 A06

resource SPI_MISO 3 C11

resource SPI_MOSI 1 A07

resource SPI_MOSI 3 C12

resource ESCSERIAL 1 B08

resource ADC_BATT 1 C03

resource ADC_RSSI 1 C00

resource ADC_CURR 1 C02

resource FLASH_CS 1 B03

resource OSD_CS 1 B14

resource GYRO_EXTI 1 B13

resource GYRO_CS 1 B12
resource USB_DETECT 1 A08
timer
timer B00 AF2
pin B00: TIM3 CH3 (AF2)
timer B01 AF2
pin B01: TIM3 CH4 (AF2)
timer A03 AF1
pin A03: TIM2 CH4 (AF1)
timer A02 AF1
pin A02: TIM2 CH3 (AF1)
timer B05 AF2
pin B05: TIM3 CH2 (AF2)
timer B07 AF2
pin B07: TIM4 CH2 (AF2)
timer C09 AF3
pin C09: TIM8 CH4 (AF3)
timer C08 AF3
pin C08: TIM8 CH3 (AF3)
timer A09 AF1
pin A09: TIM1 CH2 (AF1)
dma
dma ADC 1 0
ADC 1: DMA2 Stream 0 Channel 0
dma pin B00 0
pin B00: DMA1 Stream 7 Channel 5
dma pin B01 0
pin B01: DMA1 Stream 2 Channel 5
dma pin A03 1
pin A03: DMA1 Stream 6 Channel 3
dma pin A02 0
pin A02: DMA1 Stream 1 Channel 3
dma pin B05 0
pin B05: DMA1 Stream 5 Channel 5
dma pin B07 0
pin B07: DMA1 Stream 3 Channel 2
dma pin C09 0
pin C09: DMA2 Stream 7 Channel 7
dma pin C08 0
pin C08: DMA2 Stream 2 Channel 0
dma pin A09 0
pin A09: DMA2 Stream 6 Channel 0
feature
feature -RX_PARALLEL_PWM
feature RX_SERIAL
feature MOTOR_STOP
feature LED_STRIP
feature OSD

```
# serial
serial 4 64 115200 57600 0 115200
serial 5 1 115200 57600 0 115200
# beacon
beacon RX_SET
# led
led 0 8,8::CB:8
led 1 9,8::CB:8
led 2 10,8::CB:8
led 3 11,8::CB:8
# aux
aux 0 0 1 1300 2100 0 0
aux 1 2 1 1700 2100 0 0
# master
set dyn_notch_count = 1
set dyn_notch_q = 500
set acc_calibration = 31,16,-54,1
set mag_bustype = I2C
set mag_i2c_device = 1
set mag_hardware = NONE
set baro_bustype = I2C
set baro_i2c_device = 1
set rssi_channel = 12
set serialrx_provider = SBUS
set blackbox_device = SPIFLASH
set dshot_idle_value = 1200
set dshot_burst = ON
set dshot_bidir = ON
set motor_pwm_protocol = DSHOT300
set motor_poles = 12
set vbat_max_cell_voltage = 435
set current_meter = ADC
set battery_meter = ADC
set ibata_scale = 170
set beeper_inversion = ON
set beeper_od = OFF
set yaw_motors_reversed = ON
set pid_process_denom = 4
set osd_vbat_pos = 2337
set osd_rssi_pos = 2210
set osd_link_quality_pos = 2145
set osd_tim_1_pos = 2423
set osd_tim_2_pos = 2391
set osd_throttle_pos = 2359
set osd_vtx_channel_pos = 2177
set osd_current_pos = 2305
set osd_avg_cell_voltage_pos = 2401
set system_hse_mhz = 8
```

```
set max7456_spi_bus = 3
set dashboard_i2c_bus = 1
set pinio_box = 40,41,255,255
set flash_spi_bus = 3
set gyro_1_bustype = SPI
set gyro_1_spibus = 1
set gyro_1_sensor_align = CW270
set gyro_1_align_yaw = 2700
set gyro_2_spibus = 1
profile 0
# profile 0
set p_pitch = 32
set i_pitch = 63
set f_pitch = 80
set p_roll = 29
set i_roll = 59
set d_roll = 42
set f_roll = 76
set p_yaw = 31
set i_yaw = 63
set f_yaw = 76
set d_min_roll = 27
set d_min_pitch = 30
rateprofile 0
# end the command batch
batch end
#
SAVE
```