

**# DIFF**

**###WARNING: NO CUSTOM DEFAULTS FOUND###**

**# version**

**# Betaflight / STM32F405 (S405) 4.3.1 Jul 13 2022 / 03:32:11 (8d4f005) MSP API: 1.44**

**###ERROR IN diff: NO CONFIG FOUND###**

**# start the command batch**

**batch start**

**board\_name FLYWOO405S\_AIO**

**manufacturer\_id FLWO**

**# name: FLYWOO**

**# resources**

**resource BEEPER 1 C13**

**resource MOTOR 1 A03**

**resource MOTOR 2 B00**

**resource MOTOR 3 A02**

**resource MOTOR 4 B01**

**resource MOTOR 5 B05**

**resource MOTOR 6 B07**

**resource MOTOR 7 C09**

**resource MOTOR 8 C08**

**resource PPM 1 B08**

**resource SERIAL\_TX 1 B06**

**resource SERIAL\_TX 2 D05**

**resource SERIAL\_TX 3 B10**

**resource SERIAL\_TX 4 A00**

**resource SERIAL\_TX 6 C06**

**resource SERIAL\_RX 1 A10**

**resource SERIAL\_RX 2 D06**

**resource SERIAL\_RX 3 B11**

**resource SERIAL\_RX 4 A01**

**resource SERIAL\_RX 5 D02**

**resource SERIAL\_RX 6 C07**

**resource I2C\_SCL 1 B08**

**resource I2C\_SDA 1 B09**

**resource LED 1 C14**

**resource SPI\_SCK 1 A05**

**resource SPI\_SCK 3 C10**

**resource SPI\_MISO 1 A06**

**resource SPI\_MISO 3 C11**

**resource SPI\_MOSI 1 A07**

**resource SPI\_MOSI 3 C12**

**resource ESCSERIAL 1 B08**

**resource ADC\_BATT 1 C03**

**resource ADC\_RSSI 1 C00**

**resource ADC\_CURR 1 C02**

**resource PINIO 1 A09**

**resource FLASH\_CS 1 B03**

**resource OSD\_CS 1 B14**

resource GYRO\_EXTI 1 B13  
resource GYRO\_CS 1 B12  
resource USB\_DETECT 1 A08  
# timer  
timer B00 AF2  
# pin B00: TIM3 CH3 (AF2)  
timer B01 AF2  
# pin B01: TIM3 CH4 (AF2)  
timer A03 AF1  
# pin A03: TIM2 CH4 (AF1)  
timer A02 AF1  
# pin A02: TIM2 CH3 (AF1)  
timer B05 AF2  
# pin B05: TIM3 CH2 (AF2)  
timer B07 AF2  
# pin B07: TIM4 CH2 (AF2)  
timer C09 AF3  
# pin C09: TIM8 CH4 (AF3)  
timer C08 AF3  
# pin C08: TIM8 CH3 (AF3)  
timer A09 AF1  
# pin A09: TIM1 CH2 (AF1)  
# dma  
dma ADC 1 0  
# ADC 1: DMA2 Stream 0 Channel 0  
dma pin B00 0  
# pin B00: DMA1 Stream 7 Channel 5  
dma pin B01 0  
# pin B01: DMA1 Stream 2 Channel 5  
dma pin A03 1  
# pin A03: DMA1 Stream 6 Channel 3  
dma pin A02 0  
# pin A02: DMA1 Stream 1 Channel 3  
dma pin B05 0  
# pin B05: DMA1 Stream 5 Channel 5  
dma pin B07 0  
# pin B07: DMA1 Stream 3 Channel 2  
dma pin C09 0  
# pin C09: DMA2 Stream 7 Channel 7  
dma pin C08 0  
# pin C08: DMA2 Stream 2 Channel 0  
dma pin A09 0  
# pin A09: DMA2 Stream 6 Channel 0  
# feature  
feature -RX\_PARALLEL\_PWM  
feature RX\_SERIAL  
feature MOTOR\_STOP  
feature TELEMETRY

```
feature LED_STRIP
feature OSD
# serial
serial 0 64 115200 57600 0 115200
serial 1 1 115200 57600 0 115200
serial 3 8192 115200 57600 0 115200
# led
led 0 8,8::CB:8
led 1 9,8::CB:8
led 2 10,8::CB:8
led 3 11,8::CB:8
# aux
aux 0 0 1 1300 2100 0 0
aux 1 2 1 1700 2100 0 0
aux 2 13 0 1700 2100 0 0
aux 4 40 3 900 1300 0 0
# vtxtable
vtxtable bands 5
vtxtable channels 8
vtxtable band 1 BOSCAM_A A CUSTOM 5865 5845 5825 5805 5785 5765 5745 5725
vtxtable band 2 BOSCAM_B B CUSTOM 5733 5752 5771 5790 5809 5828 5847 5866
vtxtable band 3 BOSCAM_E E CUSTOM 5705 5685 5665 5645 5885 5905 5925 5945
vtxtable band 4 FATSHARK F CUSTOM 5740 5760 5780 5800 5820 5840 5860 5880
vtxtable band 5 RACEBAND R CUSTOM 5658 5695 5732 5769 5806 5843 5880 5917
vtxtable powerlevels 5
vtxtable powervalues 25 100 200 400 600
vtxtable powerlabels 25 50 100 200 MAX
# master
set gyro_lpf1_static_hz = 300
set gyro_lpf2_static_hz = 600
set dyn_notch_count = 0
set gyro_lpf1_dyn_min_hz = 300
set gyro_lpf1_dyn_max_hz = 600
set acc_calibration = -153,-68,-19,1
set mag_bustype = I2C
set mag_i2c_device = 1
set mag_hardware = NONE
set baro_bustype = I2C
set baro_i2c_device = 1
set rssi_channel = 12
set serialrx_provider = CRSF
set blackbox_device = SPIFLASH
set dshot_burst = ON
set motor_pwm_protocol = DSHOT300
set current_meter = ADC
set battery_meter = ADC
set ibata_scale = 90
set beeper_inversion = ON
```

```
set beeper_od = OFF
set yaw_motors_reversed = ON
set small_angle = 180
set pid_process_denom = 4
set simplified_gyro_filter_multiplier = 120
set osd_vbat_pos = 2401
set osd_rssi_pos = 2232
set osd_link_quality_pos = 2263
set osd_rssi_dbm_pos = 217
set osd_tim_1_pos = 2454
set osd_tim_2_pos = 2422
set osd_flymode_pos = 2360
set osd_throttle_pos = 2392
set osd_vtx_channel_pos = 115
set osd_current_pos = 2306
set osd_mah_drawn_pos = 2337
set osd_craft_name_pos = 2145
set osd_altitude_pos = 87
set osd_warnings_pos = 2473
set osd_avg_cell_voltage_pos = 2369
set osd_disarmed_pos = 2442
set osd_flip_arrow_pos = 2209
set osd_log_status_pos = 129
set system_hse_mhz = 8
set vtx_band = 3
set vtx_channel = 4
set vtx_power = 5
set vtx_freq = 5645
set max7456_spi_bus = 3
set dashboard_i2c_bus = 1
set pinio_box = 40,41,255,255
set flash_spi_bus = 3
set gyro_1_bustype = SPI
set gyro_1_spibus = 1
set gyro_1_sensor_align = CW90
set gyro_1_align_yaw = 900
set gyro_2_spibus = 1
set name = FLYWOO
profile 0
# profile 0
set dterm_lpf1_dyn_min_hz = 78
set dterm_lpf1_dyn_max_hz = 157
set dterm_lpf1_static_hz = 78
set dterm_lpf2_static_hz = 157
set simplified_dterm_filter_multiplier = 105
rateprofile 0
# end the command batch
batch end
```

#  
**SAVE**